

1 **From scenario to roadmap: Design and evaluation of a web-based**
2 **participatory watershed planning system for optimizing multistage**
3 **implementation plans of management practices under stepwise investment**

4 **Shen Shen¹, Cheng-Zhi Qin^{1,2,3}, Liang-Jun Zhu^{1,2,*}, A-Xing Zhu^{1,2,3,4,5}**

5 ¹State Key Laboratory of Resources and Environmental Information System, Institute of
6 Geographic Sciences and Natural Resources Research, CAS, Beijing, China

7 ²College of Resources and Environment, University of Chinese Academy of Sciences,
8 Beijing, China

9 ³Jiangsu Center for Collaborative Innovation in Geographical Information Resource
10 Development and Application, Nanjing, China

11 ⁴Department of Geography, University of Wisconsin-Madison, Madison, WI, USA

12 ⁵Key Laboratory of Virtual Geographic Environment (Ministry of Education of PRC),
13 Nanjing Normal University, Nanjing, China

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15 Corresponding author: Liang-Jun Zhu (zlj@lreis.ac.cn)

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How to facilitate non-expert stakeholders proposing stepwise investment plan for reaching agreed-upon roadmaps?



Highlights:

- System design meets practical watershed management needs for agreed-upon roadmaps
- System separates easy-to-use interface for non-expert users from specialized models
- Browser/Server system facilitates participatory processes of multiple stakeholders
- Users participate in proposing investment plans and electing optimized roadmaps
- Multi-stakeholder role-play experiment verifies system's validity and practicality

1 Abstract:

2 Planning multistage implementation plans, or roadmaps, based on the spatial
3 distribution of a best management practice (BMP) scenario is essential for
4 achieving watershed management goals under realistic conditions, such as
5 stepwise investment plans that involve multiple stakeholders, including investors,
6 economic and environmental beneficiaries. The state-of-the-art BMP roadmap
7 optimization method can address this need for optimization but is over-specialized
8 and complex to non-expert stakeholders. This study designed a user-friendly web-
9 based participatory watershed planning system to assist a diverse group of
10 stakeholders in reaching a consensus on optimal roadmaps. The participatory
11 process of stakeholders includes iteratively proposing stepwise investment
12 constraints, submitting roadmap optimization tasks, analyzing spatiotemporal
13 results from multiple perspectives, and selecting preferred roadmaps. The
14 proposed system design separates the participatory process of non-expert
15 stakeholders from the specialized modeling process of constructing simulation-
16 optimization tools for BMP roadmaps, which is done in advance by professional
17 modelers and encapsulated as webservice on the server side. The webservice
18 expose a small set of essential parameters to lower barriers to use. The interactive
19 participatory process is presented to stakeholders through web browsers with an
20 easy-to-use interface. The system design was evaluated by implementing an
21 agricultural watershed planning system for soil erosion reduction and conducting
22 a role-playing experiment involving three groups of stakeholders with different
23 standpoints in proposing investment constraints. The experimental results show

1 24 that the optimal roadmap sets exhibit progressive improvements across three-
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3 25 round optimizations started by different stakeholders, effectively capturing the
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6 26 varying perspectives of stakeholders and facilitating consensus-building among
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9 27 them. The idea of system design and example implementation can serve as a
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12 28 valuable reference for developing related user-friendly environmental decision
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15 29 support systems.

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17 30 **Keywords:**

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20 31 watershed planning; multistage implementation plan; participatory modeling;
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23 32 best management practice; scenario optimization
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1 34 **1. Introduction**

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6 36 decision support for solving environmental issues, such as soil erosion and non-
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9 37 point source pollution. Watershed planning often requires a compromise between
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12 38 multiple potentially conflicting objectives, such as maximizing eco-environmental
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15 39 effectiveness and minimizing socioeconomic investment, to reach agreed-upon
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18 40 best management practice (BMP) scenarios that satisfy standpoints of multiple
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21 41 stakeholders (e.g., investors, farmers, citizens, and authorities) (Ruiz-Ortiz et al.,
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23 42 2019; Booth et al., 2011; Reichert et al., 2015; Sun, 2013). In existing studies, a
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25
26 43 selected BMP scenario often refers to a spatial distribution of BMPs in the
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29 44 watershed. However, such a BMP scenario usually cannot be implemented at one
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32 45 time due to the constraints of practical situations, including budgets (or
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35 46 investments), local policies, willingness of landowners, and human resources
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38 47 (Abebe et al., 2019; Okumah et al., 2020; Ryan et al., 2003). Among these
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41 48 constraints, overall or stepwise investment by stakeholders may be the most
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44 49 common and comprehensive representation (Hou et al., 2020; Shen et al., 2023).
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47 50 Therefore, how to consider investment constraints that involve multiple
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50 51 stakeholders in watershed planning becomes an urgent requirement for effective
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53 52 solutions.

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56 53 A lot of BMP scenario optimization methods have been proposed to support
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59 54 watershed planning and generally take two types of approaches for considering
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62 55 stakeholder participation in the investment. The first regards all stakeholders as
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1 56 one role in proposing an overall investment constraint. They predominantly
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3 57 focused on BMP spatial optimization based on the assumption that a BMP scenario
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6 58 can be implemented simultaneously under the overall investment. Most studies on
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9 59 BMP spatial optimization aimed at cost-effective scenarios (Gaddis et al., 2014;
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11 60 Qin et al., 2018) or return on investment (Jones et al., 2017; Kroeger et al., 2019)
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14 61 fall into this category. However, this type of approach cannot further arrange the
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17 62 optimal BMP scenario into multistage implementation plans (the so-called
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20 63 practical BMP roadmap in this study), with each implementation stage including a
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23 64 BMP spatial distribution and the corresponding investment to meet the
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26 65 requirements of making actual decisions effectively.

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28 66 The second type of approach to consider stakeholder participation is setting
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31 67 stepwise investments for multiple implementation periods and conducting
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34 68 optimization in two different ways (Hou et al., 2020; Shen et al., 2023). The first
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37 69 way conducts separate optimization by stage (Hou et al., 2020; Podolak et al., 2017;
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39 70 Vogl et al., 2017). Simply put, BMP spatial configuration in each stage is treated
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42 71 as a separate optimization problem and optimized under independent geographic
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45 72 decision variables, environmental objectives, and the investment constraint (Hou
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48 73 et al., 2020). The staged optimization results were combined as a final roadmap.
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51 74 However, this type of approach only loosely combines independent optimization
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54 75 results and does not optimize the roadmap in an overall optimization problem that
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57 76 considers multistage investments. To address this weakness, a new BMP roadmap
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59 77 optimization method considering the stepwise investment and time-varying
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1 78 effectiveness of BMPs was recently proposed by Shen et al. (2023). This method
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3 79 introduces the concept of net present value (NPV) to evaluate the economic
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6 80 effectiveness of the entire roadmap and time-varying effectiveness of BMPs to
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9 81 evaluate environmental effectiveness of the roadmap. This way can effectively
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12 82 generate more feasible roadmaps from a specific BMP scenario with less
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15 83 investment burden at the cost of a slight loss of environmental effectiveness and
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18 84 thus can provide various choices with different stepwise investment constraints for
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20 85 watershed planning (Shen et al., 2023).

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22 86 However, the implementation and application of the state-of-the-art method
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25 87 involve highly specialized modeling processes, including collecting modeling data
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28 88 (e.g., watershed modeling and BMP knowledge data), improving and building the
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31 89 watershed model, and improving and executing the roadmap optimization tool
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34 90 (Shen et al., 2023). This is an iterative optimization process initiated by decision
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37 91 makers or managers determining management goals, powered by professional
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40 92 modelers utilizing scientific models and tools, and participated by stakeholders in
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43 93 multiple roles with their experience, needs, and capabilities (Babbar-Sebens et al.,
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45 94 2015; Wicki et al., 2021; Reichert et al., 2015; Voinov et al., 2016). To facilitate
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48 95 the participation of non-expert stakeholders in this process, based on pre-prepared
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51 96 specialized models by professional modelers on the backend, a watershed planning
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54 97 system that utilizes a user-friendly interface that does not require intensive
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56 98 specialized knowledge of BMP scenario analysis becomes the uncontested choice
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59 99 (Martin et al., 2016; Sugumaran et al., 2004; Walling and Vaneeckhaute, 2020).

1 100 To the best of our knowledge, no watershed planning system supports the
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3 101 overall optimization of BMP roadmaps under stepwise investment constraints
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6 102 involving multiple stakeholders. Therefore, this study aims to design a web-based
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9 103 participatory watershed planning system and evaluate its ability to iteratively assist
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12 104 various stakeholders in proposing investment constraints, optimizing roadmaps,
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14 105 analyzing results, and reaching agreed-upon plans through a case study. The basic
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17 106 idea and overall design of the system are introduced in Section 2. The case study
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20 107 of an agricultural watershed planning system for mitigating soil erosion is
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23 108 implemented in Section 3. The multistakeholder role-playing experimental design,
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26 109 results, and discussion are presented in Section 4 to verify the validity and
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29 110 practicality of this system design. Conclusions and future work are presented in
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31 111 Section 5.

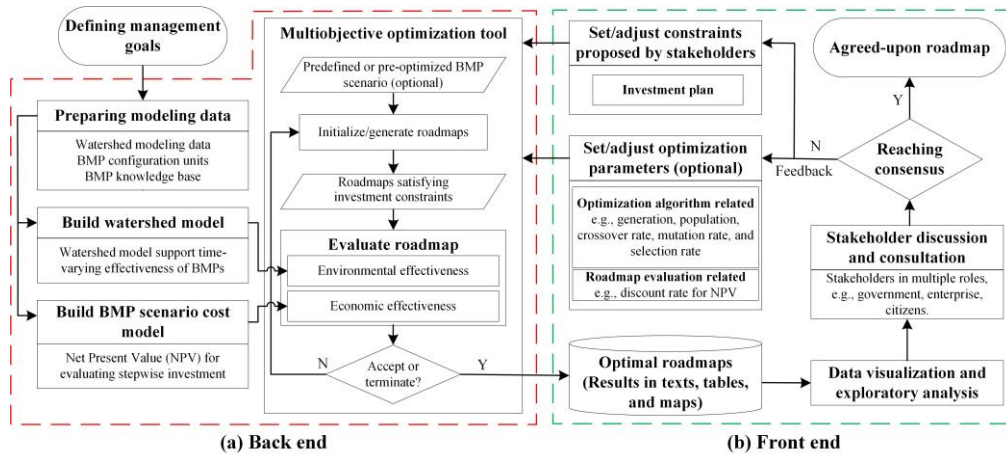
32 33 34 112 **2. Basic idea and overall design**

35 36 113 **2.1 Basic idea**

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39 114 To design a watershed planning system that allows multiple stakeholders to
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42 115 participate in proposing the investment constraints and reaching a consensus on
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45 116 optimized roadmaps of a specific BMP scenario, two key issues need to be
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48 117 addressed. The system should integrate the BMP roadmap optimizing method
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51 118 under stepwise investments while streamlining the use through inputting
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54 119 investment constraints and outputting roadmaps (Figure 1a; adapted from Shen et
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56 120 al., 2023). The workflow is an iterative optimization process of initializing,
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59 121 generating, and evaluating BMP roadmaps under the framework of an intelligent

122 optimization algorithm. The evaluations of each BMP roadmap are conducted by
 123 the customized watershed model and BMP scenario cost model according to the
 124 watershed management goals. Newly generated BMP roadmaps are screened to
 125 satisfy investment constraints before being evaluated. After the maximum iteration
 126 is reached or other conditions are satisfied, the optimization finishes and outputs
 127 optimal roadmaps (Figure 1a).

128 Next, the system must have an easy-to-use interface to facilitate the
 129 participation of stakeholders with different knowledge backgrounds and diverse
 130 roles. The participation process can be summarized as an iterative workflow:
 131 setting/adjusting investment constraints and optional optimization algorithm-
 132 based parameters, submitting the roadmap optimization task, evaluating the
 133 optimized roadmaps and comparing them with existing ones, if any, discussing and
 134 consulting among multiple stakeholders, and feeding back by adjusting investment
 135 plans or attaining agreed-upon roadmaps unanimously (Figure 1b).



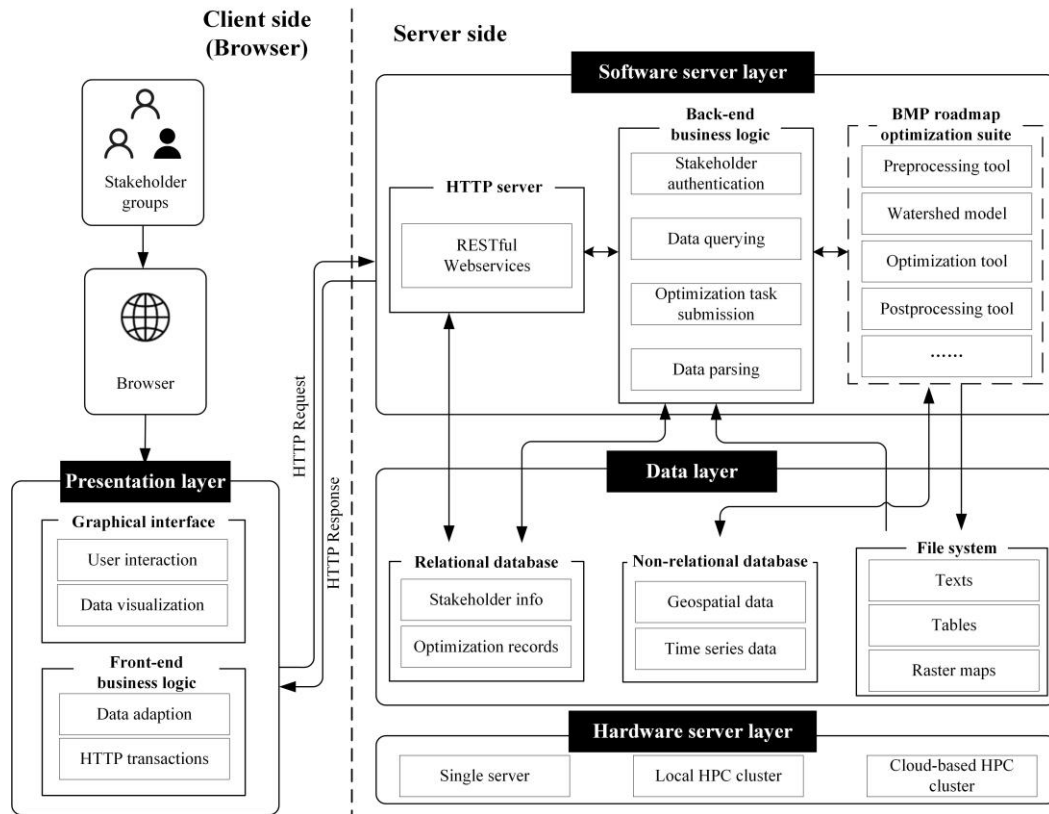
136
 137 Figure 1 Participatory optimization framework for multistage implementation
 138 plans of best management practices (BMPs) under stepwise investment: (a) BMP
 139 roadmap optimization method encapsulated in the back end (adapted from Shen
 140 et al., 2023); (b) iterative participatory workflow designed for easy-to-use front
 141 end.

1 142 Based on the basic idea and the relationship between the BMP roadmap
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3 143 optimization method and the iterative participatory workflow designed for
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6 144 stakeholders illustrated in Figure 1, Section 2.2 presents the overall architectural
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9 145 design of the participatory watershed planning system using the web application
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12 146 architecture, the mainstream architecture in promoting the development of easy-
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15 147 to-use geographic and environmental modeling applications (Chen et al., 2020;
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17 148 McDonald et al., 2019; A.X. Zhu et al., 2021). Sections 2.3–2.5 highlight three key
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20 149 functional designs of this system, including roadmap optimization method
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23 150 integration, visualization of roadmaps from spatial and temporal perspectives, and
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26 151 defining multiple stakeholder roles with diverse watershed management
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28 152 standpoints.

31 153 **2.2 Overall architecture design**

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34 154 The system adopted a layered browser/server (B/S) architecture, including
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36 155 the presentation layer on the client side (i.e., web browser) and the software server,
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39 156 data, and hardware server layers on the server side (Figure 2). The client side is
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42 157 responsible for user interaction in setting parameters before submitting the
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45 158 optimization task and exploring data of the optimized BMP roadmaps with the
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48 159 support of the front-end business logic. The business logic requests and receives
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51 160 optimized roadmaps data via the hyper-text transport protocol (HTTP) from the
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53 161 HTTP server and adapts the data structure for presentation on a graphical interface.
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56 162 The system takes the stakeholder group as the user unit and establishes a shared
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59 163 space within the group, wherein stakeholders can explore the historical optimized

164 roadmaps of all members and mark their preferred roadmaps as candidates for
 165 further discussion. The agreed-upon roadmaps can be found if a consensus can be
 166 reached, and the iterate workflow ends. Otherwise, stakeholders will propose new
 167 investment plans based on current results in the next iteration (Figure 1b).



169 Figure 2 Overall layered browser/server (B/S) architecture design of the
 170 watershed planning system

171 The server side is responsible for receiving and executing the submitted
 172 optimization tasks from the web browser, and parsing, formatting, and sending
 173 back the optimized roadmaps. The back-end business logic is the key component
 174 that handles all user-, data-, and optimization-related matters by interacting with
 175 other components or layers, including data querying, optimization task submission,
 176 and data parsing. The BMP roadmap optimization suite encapsulates models and

1 177 tools of the specific implementation of the roadmap optimization method as
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3 178 several application programming interfaces (API) to be loosely coupled with the
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6 179 business logic component (Section 2.3). HTTP server is the communication
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9 180 component responsible for communication between the server and client sides and
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11 181 within the server side. For the data layer, except for the simple file system, the
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14 182 system designs relational and non-relational databases to manage structured
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17 183 business data (e.g., stakeholder information and optimization records) and
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20 184 spatiotemporal data (e.g., geospatial and time series data), respectively. For the
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23 185 hardware server layer, the system can deploy on a single server or use the parallel
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26 186 computing capabilities of a local high-performance computing (HPC) or a cloud-
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29 187 based HPC cluster with elastic scaling capabilities to accelerate the execution of
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31 188 optimization tools.

32 33 34 189 **2.3 Integrating BMP roadmap optimization method**

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36 190 The BMP roadmap optimization method proposed by Shen et al. (2023) is
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39 191 intended to be a universal modeling framework that includes several independent
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42 192 and sequenced functional components, such as data preprocessing tools, watershed
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45 193 model and BMP scenario cost model, optimization algorithm tools, and
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48 194 postprocessing tools (Figure 1a and Figure 2). That means this framework can be
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51 195 implemented by different watershed models and optimization algorithms and
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54 196 applied for various BMPs and watershed management goals. The implementations
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57 197 of these components generally do not have user interfaces. They can be invoked
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60 198 in the API from other programs or command lines, which is unfriendly to non-

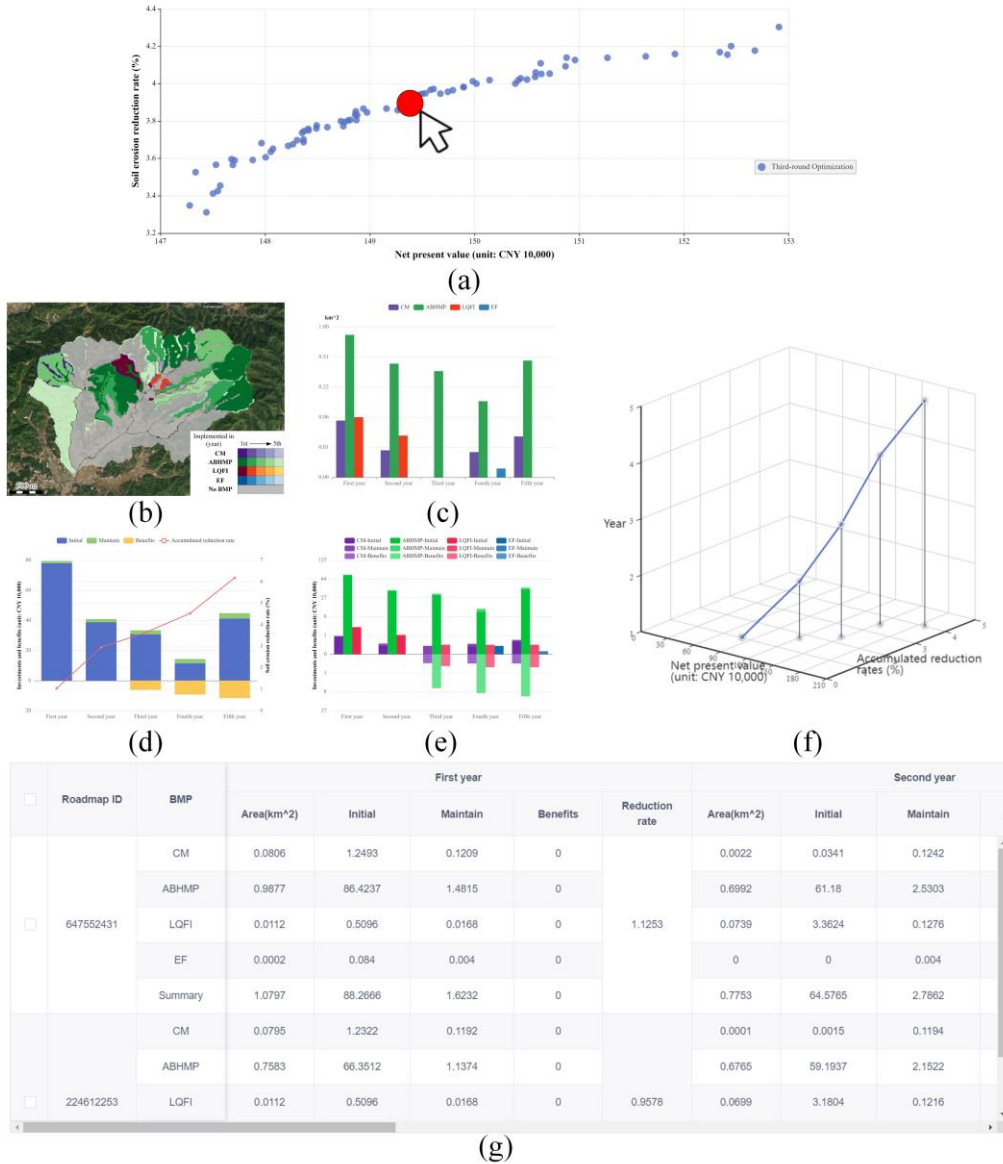
1 199 expert users but convenient for system integration.
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3 200 Therefore, several general APIs are designed for the interactions between the
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6 201 BMP roadmap optimization suite with other components, such as executing the
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9 202 optimization task with the user-specific investment plan and parsing optimized
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12 203 roadmap for visualization data. When building the watershed planning system for
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15 204 a specific case study, the specialized modeling processes according to the
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18 205 management goals should be pre-prepared by professional modelers and integrated
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21 206 with these general APIs. Hence, a new roadmap optimization task can be started
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24 207 by accepting only investment constraints proposed by stakeholders and optional
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27 208 optimization parameters (e.g., population size and maximum generation number
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30 209 of genetic algorithms) (Figure 1b). More details about the BMP roadmap
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33 210 optimization method can be found in Shen et al. (2023).

34 211 **2.4 Multi-perspective visualization of roadmaps**

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36 212 Effective spatiotemporal data visualization is crucial for stakeholders to
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39 213 understand, analyze, and reach agreed-upon roadmaps. The linked visualization
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42 214 method ensures consistent data display as stakeholders explore roadmaps (Figure
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45 215 3). By selecting a point in the Pareto front (Figure 3a), stakeholders can view
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48 216 multi-perspective data, including maps, bar and line charts, and tables. The
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51 217 mapping method considers the temporal information of BMP roadmaps, using
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54 218 different color tones to represent BMP types and color saturations to represent
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57 219 implementation time (Figure 3b). Bar charts express statistical staged information,
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60 220 such as annual construction area for each BMP type (Figure 3c) and annual

221 economic data (Figures 3d and 3e). A three-dimensional line chart shows the effect
 222 of an implementation plan at each stage (Figure 3f), and any roadmap can be added
 223 to a well-designed data table for comparison (Figure 3g).



224
 225 Figure 3 Spatiotemporal data visualization for selected roadmap: (a) visualization
 226 and interactive mode of Pareto front; (b) a map of multistage BMP spatial
 227 distributions, wherein different color tones represent different BMP types, and
 228 the saturations from dark to light represent the implementation time (e.g., from
 229 the first year to the fifth year); (c) the annual construction area for each BMP
 230 type; (d) the total initial construction cost, maintenance cost, and income by year;
 231 (e) subdivides these data by BMP types; (f) the stepwise economic and
 232 environmental effectiveness that a roadmap can reached at each stage; (g) the
 233 well-designed table containing detailed roadmap data for comparative analysis.

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234 **2.5 Stakeholder roles designed in participatory planning**

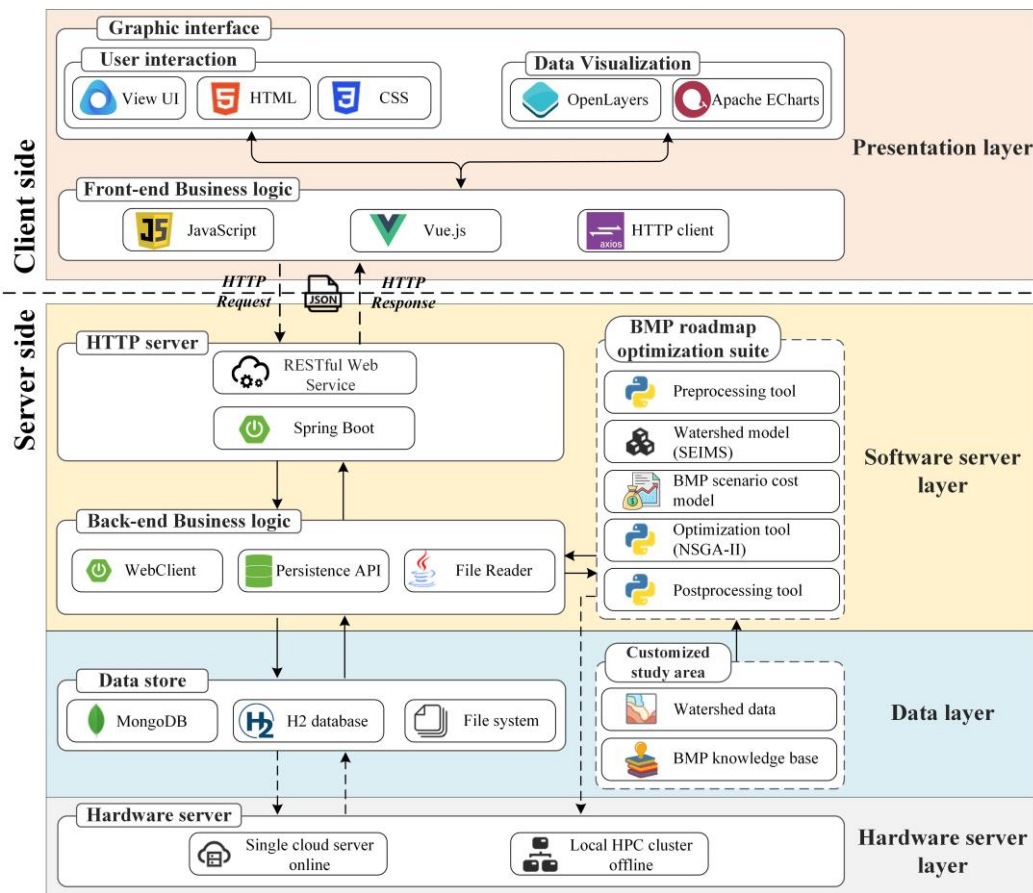
235 Public–private partnership between a government agency and a private sector
236 company or individual business is one of the most used management modes of
237 special funds for watershed management projects, such as soil and water
238 conservation (Qian et al., 2020). The government provides funds to social groups
239 (e.g., enterprises) or individuals (e.g., governance professionals) through subsidies
240 or incentives to conduct projects. Enterprises or governance professionals
241 (hereinafter referred to as enterprises) invest additional funds on their own to
242 implement management practices within the scope of policies and regulations and
243 enjoy the economic benefits of these practices.

244 Therefore, this system design considers three stakeholder roles: investors,
245 economic beneficiaries, and environmental beneficiaries. Accordingly, we
246 designed a stakeholder group with the three stakeholders: 1) the government
247 stakeholder is the primary investor and environmental beneficiary; 2) the
248 enterprise stakeholder is both a co-investor and an economic beneficiary, focusing
249 on the balance between cost and benefit; and 3) the other stakeholders from
250 ordinary farmers and citizens living in the watershed can be primarily considered
251 as environmental beneficiaries.

252 **3. Case study of an agricultural watershed planning system for mitigating**
253 **soil erosion**

254 Based on the above overall design, we chose a small agricultural watershed
255 planning case study for soil erosion reduction as an example to develop the

256 watershed planning system, which can be accessed via <http://easygeoc.net:9091/>.
 257 This system is open-source via Github (refer to Data and code availability section
 258 for more details). The technical selections are prevailing frameworks (e.g., Spring
 259 Boot and Vue.js), software (e.g., MongoDB database), programming languages
 260 (e.g., Java, JavaScript, Python, and C++), and self-developed BMP roadmap
 261 optimization suite by Shen et al. (2023), as shown detailed in Figure 4.



262
 263 Figure 4 Overall technical schematic diagram of the watershed planning
 264 system implemented in the Youwuzhen watershed case study
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3.1 Overall implementation

On the server side, the implementation of the BMP roadmap optimization suite by Zhu and Shen et al. (2022) was integrated, including the calibrated watershed model and roadmap optimization tool based on the latest version of SEIMS (spatially explicit integrated modeling system) that supports evaluating the environmental effectiveness of the multistage BMP implementation plan using time-varying effectiveness of BMPs (Zhu et al., 2019a; Shen et al., 2023). According to the available modeling data and settings of the previous study (Shen et al., 2023), the period for watershed simulations was from 2011 to 2017, and the implementation period for BMP roadmaps was from 2012 to 2016. The process of executing the optimization task via Python APIs is as follows (Figure 4): The stepwise investment constraints and optimization parameters are organized into a JSON (JavaScript Object Notation) string and sent to the HTTP server by post request. Next, the HTTP server received the JSON object and converted it into a Java object. Then, the WebClient is instanced and configured to send the optimization request and its parameters to the optimization suite through web services API. Subsequently, when the optimization suite completed the optimization task, the running status is returned to the WebClient and the results are written into the data store server in the files and database records. The FileReader reads the files and constructs a new Java object, which is converted to a JSON string and returned to the client side via the HTTP response.

We implemented the optimization task execution in online and offline modes

1 288 using two hardware architectures to deal with different application tasks. When
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3 289 the optimization task can be completed quickly (e.g., a case study in a small area
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6 290 with coarse-resolution data), the online mode is activated, where the optimization
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9 291 suite runs on a single cloud server. For performance reasons, we currently restrict
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12 292 the total number of model executions to 20 and use 30 m resolution data in online
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15 293 mode to ensure that optimization tasks can be completed in less than 10 minutes.
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17 294 That is, only optimization tasks with the product of evolutionary generations and
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20 295 population size less than or equal to 20 can be executed online (e.g., optimization
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23 296 of five generations with four individuals in the initial generation). Alternatively, to
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26 297 improve the computing efficiency of a compute-intensive case study, the offline
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29 298 mode is adopted, where the administrator manually submits the optimization task
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32 299 in the local HPC cluster. The system will email the user once the optimization task
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34 300 is finished.

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36 301 On the client side, the entire graphical interface (Figure 5) was implemented
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39 302 based on HTML5 and CSS 3, and the View UI, a component library based on
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42 303 Vue.js, was utilized for rapid prototyping. The OpenLayers and Apache Echarts
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45 304 were used to visualize the roadmap spatial dimensions and bar and three-
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48 305 dimensional line charts, respectively.
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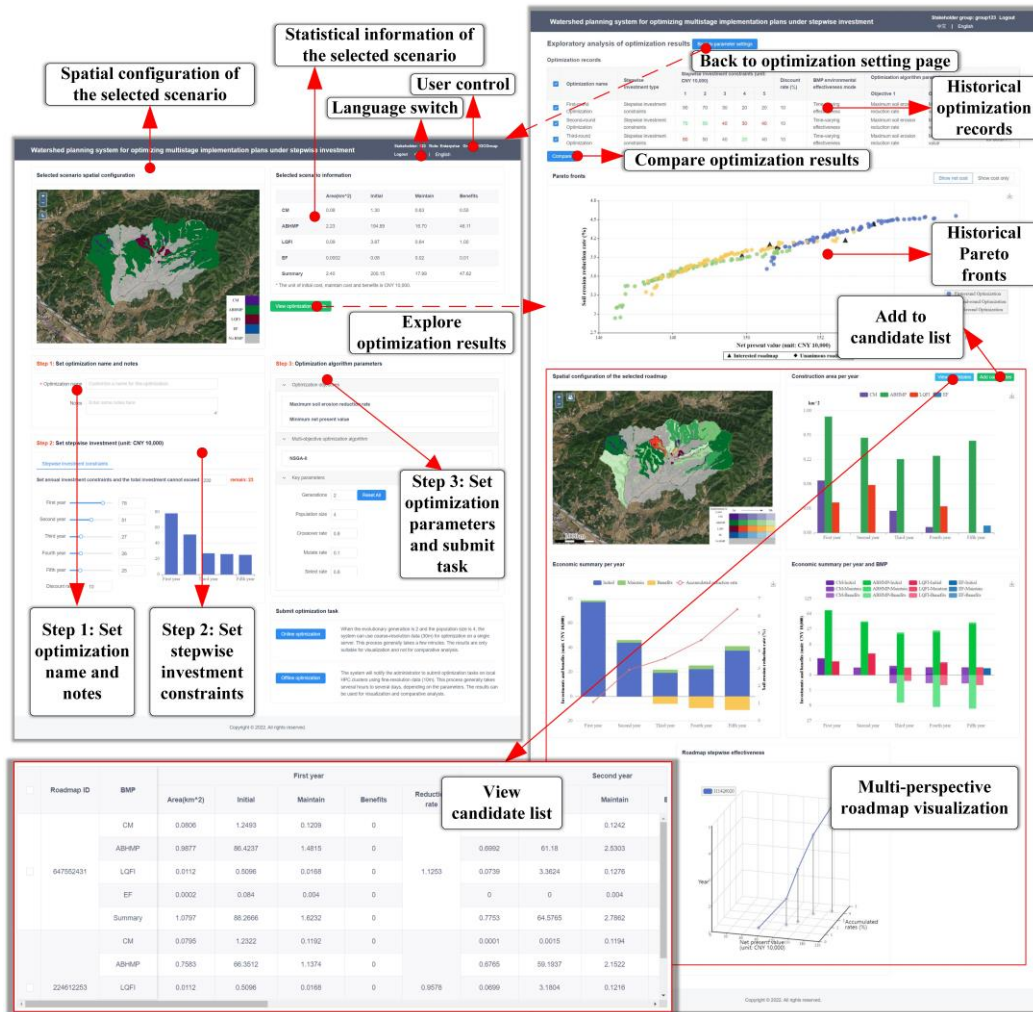


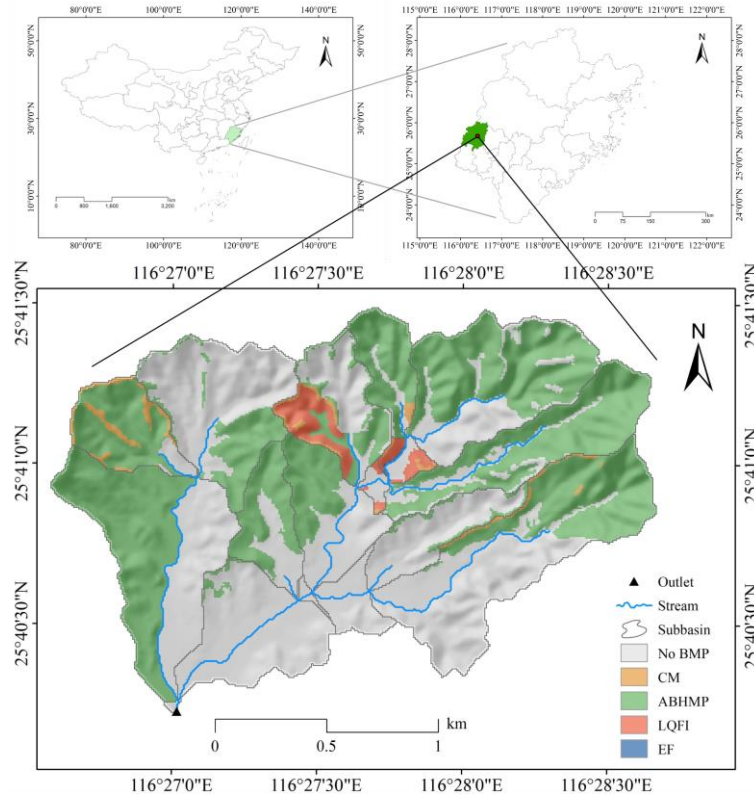
Figure 5 The client-side graphical user interface of the Youwuzhen watershed planning system

3.2 Study area and watershed management goal

The Youwuzhen watershed (approximately 5.39 km²) in Changting County, Fujian Province, China, was chosen as the study area (Figure 6). The primary geomorphological characteristics are the low mountains and hills with steep slopes (up to 52.9° and with an average slope of 16.8° in the watershed) and broad alluvial valleys (Qin et al., 2018). The study area has a mid-subtropical monsoon moist climate, with an annual average temperature of 18.3 °C and precipitation of 1697 mm. Precipitation is characterized by concentrated and intense thunderstorm events, contributing about three-quarters of the annual precipitation from March

1 318 to August. The mainland-use types were forests, paddy fields, and orchards, with
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3 319 area ratios of 59.8, 20.6, and 12.8%, respectively. Additionally, the forests in the
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6 320 study area are dominated by secondary or human-made forests with scattered
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9 321 Masson's pine (*Pinus massoniana*). The soil types were red soil (78.4%), majorly
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11 322 distributed in hilly regions, and paddy soil (21.6%) in valleys (Chen et al., 2013,
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14 323 2017). The red soil, originating from granite, underwent substantial weathering,
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17 324 rendering it inherently lacking essential nutrients, deficient organic matter content,
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20 325 and limited capacity to hold water and thus vulnerable to erosion. As a result of
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23 326 the above natural conditions and long-term human activities (e.g., forest
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26 327 destruction), this area has become one of the most severely eroded counties in the
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29 328 granite-red soil region of southern China (Chen et al., 2013).

30 329 The watershed management goal in the Youwuzhen watershed in this case
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33 330 study is maximizing the soil erosion reduction rate and minimizing the investment.
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36 331 The modeling process of this watershed planning optimization application adopts
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39 332 the work of Shen et al. (2023) and is briefly introduced in the following subsection.
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334
335 Figure 6 Map of Youwuzhen watershed in Changting County, Fujian Province,
336 China, and spatial distribution of the fundamental best management practice
337 (BMP) scenario based on slope position units derived from Zhu et al. (2019b).
338 Four BMPs are included: closing measures (CM), arbor–bush–herb mixed
339 plantation (ABHMP), low-quality forest improvement (LQFI), and economic
340 fruit (EF).

341 3.3 Preparation for the Youwuzhen watershed planning system

342 This section presents the data, models, and tools required for the watershed
343 planning system customized for the Youwuzhen case study.

344 3.3.1 Basic geographic data collection

345 The basic spatial data collected for Youwuzhen watershed modeling included
346 a gridded digital elevation model, land-use type map, and soil type map, all of
347 which were unified to a 10 m resolution (Qin et al., 2018). Property lookup tables
348 for land use/land cover and soil were prepared according to our previous studies
349 (Qin et al., 2018; Zhu et al., 2019b) (refer to Data and code availability section for
350 more details). Daily climate data, including temperature, relative moisture, wind

1 351 speed, and sunshine duration from 2011 to 2017, were derived from the National
2
3 352 Meteorological Information Center of the China Meteorological Administration.
4
5
6 353 Daily precipitation data were obtained from local monitoring stations. Streamflow
7
8
9 354 and sediment discharge data from 2011 to 2017 at the watershed outlet periodic
10
11 355 site were provided by the Soil and Water Conservation Bureau of Changting
12
13
14 356 County.

16 357 **3.3.2 BMP knowledge base**

18 358 In this study area, four representative BMPs have been vastly implemented
19
20
21 359 for soil and water conservation: closing measures (CM), arbor–bush–herb mixed
22
23
24 360 plantation (ABHMP), low-quality forest improvement (LQFI), and economic fruit
25
26
27 361 (EF) (Figure 6). Their brief descriptions were adapted from Zhu et al. (2019b) and
28
29
30 362 are enlisted in the Appendix (Table A.1).

32 363 The BMP knowledge base comprises spatial configuration knowledge (e.g.,
33
34
35 364 suitable locations of each BMP and spatial relationships among BMPs),
36
37
38 365 environmental effectiveness and economic effectiveness data (Qin et al., 2018).
39
40
41 366 The first knowledge type is used for spatial optimization of BMPs to derive the
42
43
44 367 cost-effective BMP scenario (Zhu et al., 2019b). The pre-optimized BMP scenario
45
46
47 368 is included in this case study for roadmap optimization. Detailed BMP
48
49
50 369 environmental effectiveness and cost-benefit data adapted from Shen et al. (2023)
51
52
53 370 can be found in Table A.2 of the Appendix. The cost-benefit data include initial
54
55
56 371 construction cost (one-time cost only in the first year of implementation),
57
58
59 372 maintenance cost (annual cost after implementation), and benefits (direct
60
61
62 373 economic benefits (e.g., fruit production growth, forest stock volume) computed

1 374 starting from the third (e.g., CM, ABHMP, and LQFI) or fifth year (e.g., EF) after
2
3 375 implementation).

4 376 **3.3.3 Calibrated watershed model and the selected scenario for roadmap optimization**

5
6
7 377 We constructed and calibrated a daily SEIMS-based watershed model that
8
9
10 378 utilizes gridded cells as the basic simulation unit to simulate daily soil erosion in
11
12
13 379 the Youwuzhen watershed. The elaborated modeling process is not the core content
14
15
16 380 of this study, which will not be repeated, and the details can be found in Zhu et al.
17
18
19 381 (2019b).

20
21 382 We selected an optimized BMP scenario from Zhu et al. (2019b) as the
22
23
24 383 fundamental spatial scenario for optimizing the implementation plans (Figure 6).
25
26
27 384 The scenario uses a simple system of three types of slope positions (ridge,
28
29
30 385 backslope, and valley) as BMP configuration units, which have been proven to be
31
32
33 386 effective in our previous studies (Qin et al., 2018; Zhu et al., 2019b; L.J. Zhu et
34
35
36 387 al., 2021).

37 388 **3.3.4 Multi-objective optimization method for roadmaps**

38
39
40 390 The multi-objective in this case study refers to maximizing the soil erosion
41
42
43 391 reduction rate and minimizing the roadmap discounted net cost (i.e., net present
44
45
46 392 value (NPV)). The NPV introduced into the BMP cost model can reasonably
47
48
49 393 evaluate the investment process by integrating multistage investments into a
50
51
52 394 numerical indicator (Shen et al., 2023). A generalized roadmap spatial
53
54
55 395 optimization problem can be formulated as:

$$56
57 396 \min\{-f(R), g(R)\} \quad (1),$$

$$f(R) = \sum_{t=1}^q f(R, t) / q = \sum_{t=1}^q \frac{V(0) - V(R, t)}{V(0)} \times 100\% / q \quad (2),$$

$$g(R) = \sum_{t=1}^q \frac{O_t - F_t}{(1+r)^t} \quad (3),$$

$$O_t = \sum_{k=1}^n O(S, k, t) = \sum_{k=1}^n \begin{cases} A(X(k), t) * \{C(X(k)) + M(X(k), t)\}, & \text{if } t \geq T(k) \\ 0, & \text{if } t < T(k) \end{cases} \quad (4),$$

$$F_t = \sum_{k=1}^n F(S, k, t) = \sum_{k=1}^n \begin{cases} A(X(k), t) * B(X(k), t), & \text{if } t > T(k) \\ 0, & \text{if } t \leq T(k) \end{cases} \quad (5),$$

where $f(R)$ is the average soil erosion reduction rate after implementing roadmap R during the implementation period (Equation 2), and $g(R)$ is the NPV in the first year of roadmap R (Equation 3). t is the implementation period, q is the total number of time periods, $f(R, t)$ represents the soil erosion reduction rate within period t , and $V(0)$ and $V(R, t)$ are the total amounts of sediment yields from the hillslope routed into the channel (kg) under the baseline scenario and scenario in roadmap R in period t , respectively. O_t and F_t are cash outflow and inflow during period t , which can be computed using the configured BMP area on the k th spatial unit $A(X(k), t)$, the initial construction cost $C(X(k))$, maintenance cost $M(X(k), t)$, and benefits of BMPs implemented in this period and before $B(X(k), t)$; and r is the discount rate set by the investor or project manager (e.g., 10%) (Khan and Jain, 1999; Žižlavský, 2014).

The vastly used non-dominated sorting genetic algorithm (NSGA-II) (Deb et al., 2002) was adopted as the intelligent optimization algorithm by the BMP implementation order optimization suite (Shen et al., 2023).

1 418 **4 Experimental design and evaluation**

2
3 419 **4.1 Experimental design**

4
5
6 420 A multistakeholder role-playing experiment was designed to verify that the
7
8
9 421 watershed planning system constructed in this study can assist stakeholders to
10
11 422 participate in proposing stepwise investment constraints to develop agreed-upon
12
13 423 roadmaps. The experiment assumed three stakeholder roles (see Section 2.5) and
14
15 424 analyzed possible participatory behaviors from the perspective of their role
16
17 425 characteristics and specific needs. To reach a consensus faster between
18
19 426 stakeholders, the experiment assumed that stakeholders participate in the decision-
20
21 427 making process in a particular order, and each stakeholder can refer to the previous
22
23 428 optimization results before initiation. A typical participation order was designed
24
25 429 as follows: 1) government, 2) enterprise, and 3) other stakeholders (e.g., citizens
26
27 430 living in the watershed). This order represents a prevalent cooperation mode in the
28
29 431 local area and is adjustable. Diverse participation orders may affect the roadmaps
30
31 432 in the optimization results, but this does not obstruct multiple stakeholders from
32
33 433 reaching a consensus. The optimization results obtained by multiple stakeholders
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35 434 with diverse roles should reflect their actual requirements. The detailed
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37 435 participatory process was designed as follows:

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49
50 436 1) The government stakeholder is the primary investor who leads the first-
51
52 437 round optimization and discussion with the standpoint of striving for as much
53
54 438 environmental effectiveness as possible with as little investment pressure as
55
56 439 possible. Since the selected fundamental spatial scenario requires a total
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1 440 investment of 218.14 (with the unit of CNY 10,000; similarly hereinafter) and an
2
3 441 income of 47.62 during the five-year implementation period, we slightly increased
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6 442 the overall investment constraint to 230. Based on this, a regular stepwise
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9 443 investment constraint is proposed as 90, 70, 30, 20, and 20 for the five-year
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11
12 444 implementation (the NPV without income is 188.29).

13
14 445 2) The second-round optimization is launched by the enterprise stakeholder
15
16
17 446 based on the elected roadmaps by the government stakeholder. The enterprise
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19
20 447 stakeholder is both investor and economic beneficiary who expects initial
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23 448 investment pressure reduction in the implementation plan.

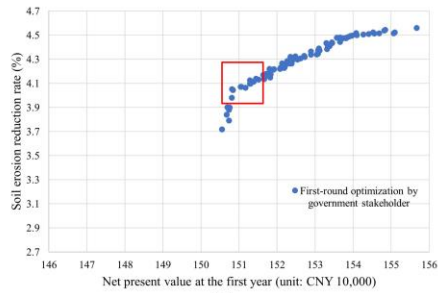
24
25 449 3) The third-round optimization is conducted by other stakeholders (e.g.,
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27
28 450 citizens living in the watershed) who pay more attention to improving
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30
31 451 environmental improvement.

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33
34 452 After the above three rounds of optimizations and discussions with the
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36
37 453 cooperation of the three stakeholders, the optimized roadmaps should primarily
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39
40 454 meet all their requirements.

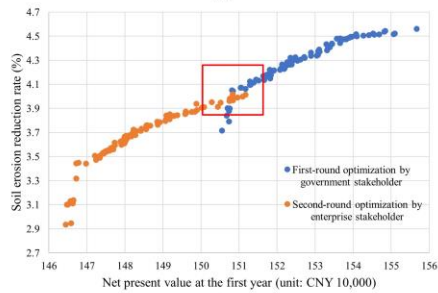
41 455 **4.2 Experimental results and discussions**

42 456 **4.2.1 Effectiveness of iterative optimization process in the system**

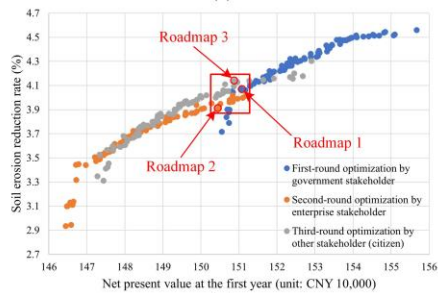
43
44
45
46 457 After each of the above optimizations and discussions among stakeholders, a
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48
49 458 candidate range of multi-objective can be built by stakeholders, from which
50
51
52 459 agreed-upon roadmaps can be determined. Figure 7 depicts the Pareto fronts
53
54
55 460 derived from the three optimization rounds in turn, with the candidate ranges of
56
57
58 461 multi-objective marked as red rectangles. The process of each optimization round
59
60
61 462 is described in detail below.



(a)



(b)



(c)

Figure 7 Pareto fronts of the three optimization rounds launched by three stakeholder groups

The first-round optimization by government stakeholders showed an obvious inflection point at an NPV of approximately 151 (Figure 7a). As the Pareto fronts NPV decreased, the soil erosion reduction rate gradually decreased, but declined rapidly post the inflection point. The annual investment of roadmaps (visualized in the form of Figure 3d) on the left of the inflection point indicated this phenomenon is caused by the low investment in the first year than the second (Shen et al., 2023). Roadmaps near the inflection point (in the red box) are most likely given priority by the government stakeholders.

On the basis of reducing the first-year investment but still being greater than

1 475 the second year, the enterprise stakeholder proposed a modified investment plan
2
3 476 to start the second-round optimization, i.e., 70, 50, 40, 30, and 40 and the NPV
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5
6 477 without income is 180.34. As shown in Figure 7b, compared to the first-round
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8
9 478 Pareto front, the new Pareto front moves to the lower left as a whole, which means
10
11
12 479 that these roadmaps sacrifice some environmental effectiveness in exchange for
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14
15 480 lower investment pressures.

16
17 481 The exploratory analysis of the previous results showed that among roadmaps
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19
20 482 with similar investment plans in the first three years, a higher investment in the
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23 483 fifth year than the fourth year often results in a slightly higher soil erosion
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25
26 484 reduction rate. Therefore, to further achieve higher environmental effectiveness,
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28
29 485 the other stakeholders proposed a revised investment constraint by reducing part
30
31
32 486 of the fourth-year investment and increasing it in the first-year and keep the fifth-
33
34
35 487 year unchanged, i.e., 80, 50, 40, 20, and 40 and the NPV without income is 182.60.
36
37
38 488 The optimization results indeed validated the proposal that further improvements
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40
41
42 489 in the comprehensive effectiveness of roadmaps occurred within the candidate
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44
45 490 range of multi-objective (red box in Figure 7c).

46
47
48 491 Therefore, the final optimization results can well meet the standpoints and
49
50
51 492 investment proposals of all stakeholder groups. The progressive shifts in the three
52
53
54 493 optimized roadmap sets can well reflect the differences in standpoints among
55
56
57 494 stakeholders and facilitate the reach of agreed-upon solutions, demonstrating the
58
59
60 495 effectiveness of the iterative participatory process in the system.

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497

498 4.2.2 The rationality and diversity of the optimized roadmaps

1
2 499 The overlapping part among multiple Pareto fronts is often the focus of
3
4
5 500 discussions among all stakeholder groups, and is also a potential area where
6
7 501 agreed-upon solutions can be reached. In this experiment, the scope of this
8
9
10 502 candidate area was focused step by step (the red box in Figures 7a–c) and the
11
12
13 503 investment-environmental effectiveness differences between the roadmaps in the
14
15
16 504 area were no longer apparent, indicating that the agreed-upon roadmaps is most
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18
19 505 likely to be elected within this area. Meanwhile, there were still some differences
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21
22 506 among the roadmaps, reflecting the diversity of the Pareto solution sets. Three
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25 507 representative roadmaps were selected from the candidate area in Figure 7c, one
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27
28 508 for each Pareto front, and their spatiotemporal implementation configurations,
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31 509 stepwise investments, and economic benefits were compared to illustrate their
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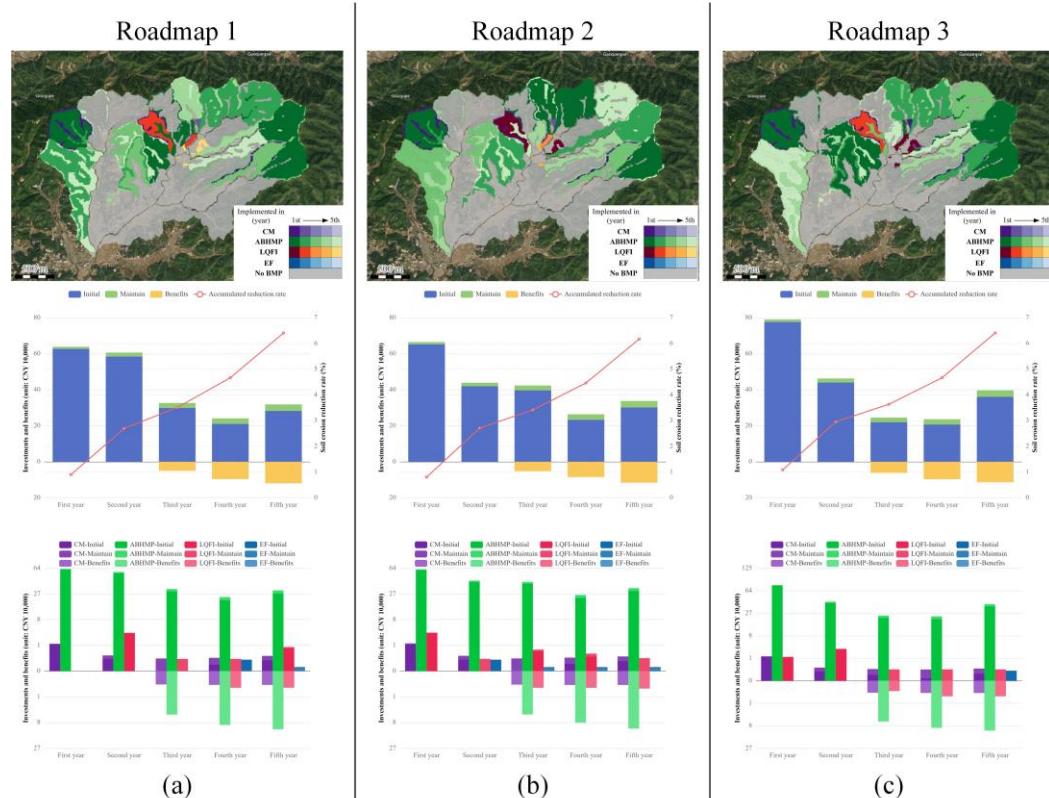


Figure 8 Three representative roadmaps selected from candidate area after three round optimizations, one for each Pareto front. The map in the first row demonstrates the BMP spatiotemporal configuration in the roadmap. The bar chart in the second row demonstrates the annual investment and income, and the line chart demonstrates the yearly soil erosion reduction rate. The bar chart in the third row demonstrates detailed investment and income annually of each BMP.

Compared with roadmap#1 derived by the government stakeholder, roadmap#2 by the enterprise stakeholder reduced investment in the second year (also in the first two years) and thus led to a lower environmental effectiveness. Roadmap#3 from the third-round optimization obtained the highest environmental effectiveness with a maximum first-year investment, lowest fourth-year investment, and highest fifth-year investment. Thus, roadmap#3 or similar roadmaps are more likely to become the final agreed-upon roadmap.

The roadmap optimization results affected by stepwise investment plans can

1 526 be explained by the particularity of the BMPs selected in this case study. In the
2
3 527 selected fundamental spatial scenario (Figure 6), ABHMP occupied the most
4
5
6 528 prominent area. This BMP can take effect quickly post implementation, and
7
8
9 529 slightly decrease and then remain stable (see Appendix Table A.2). The
10
11 530 environmental effectiveness of the ABHMP peaked in the first year. Therefore,
12
13
14 531 roadmap#3 tended to deploy more ABHMP in the last year of the project
15
16
17 532 implementation period, which not only ensures good environmental effectiveness,
18
19
20 533 but also reduces the overall investment as the fifth-year investment after
21
22
23 534 discounting is smaller than investments in other years.

535 **4.3 Evaluation of the designed and implemented watershed planning system**

536 To facilitate the successful development of environmental decision support
537 systems (EDSS), Walling and Vaneekhaute (2020) identified 13 major challenges
538 from stakeholder-, model-, and system-oriented perspectives and proposed
539 evaluation criteria for EDSSs accordingly. For example, identifying stakeholders
540 and prioritizing their influence and participation are primary challenges from the
541 stakeholder-oriented perspective. Based on this, we briefly evaluated the
542 watershed planning system designed and implemented in this study.

543 From the stakeholder-oriented perspective, with the focus of assisting the
544 participation of multistakeholder in proposing different investment plans to derive
545 agreed-upon BMP roadmaps, this system identified three types of stakeholders,
546 including investors, economic beneficiaries, and environmental beneficiaries and
547 designed three stakeholder groups to simulate the role-playing experiment. The

1 548 case study indicated that this system could provide effective comprehensibility of
2
3 549 optimized roadmaps through spatiotemporal data visualization. The successful
4
5
6 550 role-playing experiment designed and conducted according to the practical needs
7
8
9 551 provided confidence in participation for stakeholders.

10
11 552 From the model-oriented perspective, the premise of this system is the
12
13
14 553 accurate definition and modeling of BMP roadmap optimization problems by
15
16
17 554 professional modelers. Based on this, stakeholders only need to propose the
18
19
20 555 investment constraint to trigger the execution of the specialized roadmap
21
22
23 556 optimization task, which generates multiple near-optimal solutions for evaluation
24
25
26 557 and discussion. After three rounds of optimization and discussion, roadmaps that
27
28
29 558 met the requirements of the stakeholders continued to emerge, and the
30
31
32 559 comprehensive effectiveness gradually improved. The Pareto fronts in the
33
34 560 candidate area in Figure 7 reflect the improvement process of comprehensive
35
36
37 561 effectiveness. Therefore, professional modelers guarantee the accuracy of the
38
39
40 562 roadmap optimization suite, and the system provides convincing and simplified
41
42 563 usage.

43
44 564 From the system-oriented perspective, the iterative workflow provides
45
46
47 565 sufficient technical support for the sequential participation of the three stakeholder
48
49
50 566 groups in the case study. Multi-perspective linked visualization effectively allows
51
52
53 567 stakeholders to compare, evaluate, and comprehend multistage implementation
54
55
56 568 plans, which also stimulates stakeholders to propose new ideas in decision-making.
57
58
59 569 Simple interactions and rich spatiotemporal visualizations designed in the system

1 570 satisfy stakeholder requirements to evaluate the roadmap. The parallel computing
2
3 571 adopted by the roadmap optimization suite and the HPC hardware in the offline
4
5
6 572 mode saves time in arriving at the results. Most importantly, the B/S structure of
7
8
9 573 the system ensures that there is no barrier for stakeholders to access.

10
11 574 Overall, the proposed design and case study of a watershed planning
12
13 575 system could effectively promote the application of the state-of-the-art BMP
14
15
16 576 roadmap optimization method among multiple stakeholders with different
17
18
19 577 standpoints. Technically, any selected BMPs and customized watershed model in
20
21
22 578 any study area aiming at various watershed management needs can be applied to
23
24
25 579 the method proposed by Shen et al. (2023) and the system proposed in this study.
26
27
28 580 Except for the basic structure of the system, including the encapsulated roadmap
29
30
31 581 optimization suite on the back end and the user-friendly interactive workflow and
32
33
34 582 spatiotemporal data visualization, many details of the system implementation can
35
36
37 583 be adjusted by developers. For example, watershed management goals, the
38
39
40 584 accordingly customized multi-objective optimization tool (e.g., Kumeda et al.,
41
42
43 585 2021), the watershed model (e.g., SWAT model), and selected BMPs and their
44
45
46 586 representation in the watershed model.

47 587 **5. Conclusions and future works**

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49
50 588 This study proposed the design and evaluation of a web-based participatory
51
52
53 589 watershed planning system for optimizing multistage implementation plans of
54
55
56 590 BMPs, i.e., from the BMP scenario to roadmaps. The system is oriented to the
57
58
59 591 practical watershed management needs for agreed-upon roadmaps involving

1 592 multiple stakeholders and aiming at promoting the application of the state-of-the-
2
3 593 art BMP roadmap optimization method. The design separates easy-to-use
4
5
6 594 interfaces for non-expert stakeholders from specialized models pre-prepared by
7
8
9 595 professional modelers and encapsulated on the back end. The system
10
11
12 596 implementation comprises server and client sides with independent technical
13
14
15 597 routes. The design was demonstrated in an agricultural watershed planning case
16
17
18 598 study for soil erosion reduction. The validity and practicality of the case study
19
20
21 599 system were verified through the role-playing experimental design of three
22
23 600 stakeholder groups (i.e., government, enterprise, and other stakeholders such as
24
25 601 citizens).

26
27
28 602 The system design has high flexibility and is easy to implement. The
29
30
31 603 watershed model and optimization tool in the optimization suite can be replaced
32
33
34 604 with components having similar functionality. The loosely coupled frontend and
35
36
37 605 backend design allows interface-oriented programming to be applied regardless of
38
39
40 606 specific programming languages and implementation details. The input and output
41
42
43 607 data utilized in the system are in text format (e.g., text, comma-separated values),
44
45
46 608 independent of the programming language. Network transmission data are based
47
48
49 609 on standard data-exchange formats (e.g., JSON). Therefore, system
50
51
52 610 implementation can be customized for applications in other study areas with only
53
54
55 611 a few technical or engineering changes. Moreover, the system design and example
56
57
58 612 implementation can serve as a suitable platform for inspiring the simulation-and-
59
60
61 613 optimization-based decision-making thinking of students taking environmental

1 614 management-related courses.
2
3 615 As intended to be a general watershed planning system providing roadmap
4
5
6 616 planning for non-expert stakeholders, several issues or limitations still require
7
8
9 617 further study. The most important ones may include: (1) developing an integrated
10
11 618 modeling platform to enable watershed planning systems and preceding watershed
12
13
14 619 modeling systems cannot only work independently but also be seamlessly
15
16
17 620 connected; (2) enriching parameter configuration during the optimization process
18
19
20 621 for a specific application, including more options for optimization algorithms,
21
22 622 multi-perspective constraints, and governance objectives, to meet diverse
23
24
25 623 stakeholder needs with reasonable simplification; and (3) employing a cloud-
26
27
28 624 native architecture to implement the design idea of this study to improve the
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31 625 system performance. Besides, we appeal to enhance long-term monitoring of the
32
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34 626 time-varying effectiveness of BMP routinely after implementation and applying
35
36
37 627 the data in related studies of BMP scenario analysis.
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628

629 **Data and code availability**

630 The source code of the Youwuzhen watershed planning system is open-source
631 at GitHub (<https://github.com/lreis2415/WatershedPlanningSystem>), and the
632 front- and back-end projects are located in the mip-wps-web and mip-wps-service
633 folders, respectively. The improved SEIMS programs and the prepared data
634 encapsulated in the back end are freely available at Shen and Zhu (2022). The
635 Youwuzhen watershed spatiotemporal datasets are in the
636 /SEIMS/data/youwuzhen/data_prepare folder, including meteorological data,
637 property lookup tables of landuse/landcover and soil, spatial data, and BMP
638 knowledge data, etc.

639 **Acknowledgements**

640 This work was supported by the National Key Research and Development

641 Program of China (Project No.: 2021YFB3900904), Chinese Academy of
642 Sciences (Project No.: XDA23100503), National Natural Science Foundation of
643 China (Project No.: 41871362, 42101480, and 41871300), Key Project of
644 Innovation LREIS (Project No.: KPI003), and 111 Program of China (Approval
645 Number: D19002).

646 The support for A-Xing Zhu through the Vilas Associate Award, the Hammel
647 Faculty Fellow Award, and the Manasse Chair Professorship from the University
648 of Wisconsin-Madison is greatly appreciated.

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Supplementary materials on brief descriptions, environmental effectiveness data, and cost-benefit data of the four best management practices (BMPs) considered in this study

Table A.1 Brief descriptions of the four BMPs considered in this study (adapted from Zhu et al. (2019b) and photos from Chen et al. (2013)). These representative BMPs have been widely implemented for soil and water conservation in this study area.


BMP	Photo	Brief description
Closing measures (CM)		Closing the ridge area and/or upslope positions from human disturbance (e.g., tree felling and forbidding grazing) to facilitate afforestation.
Arbor-bush-herb mixed plantation (ABHMP)		Planting trees (e.g., <i>Schima superba</i> and <i>Liquidambar formosana</i>), bushes (e.g., <i>Lespedeza bicolor</i>), and herbs (e.g., <i>Paspalum wettsteinii</i>) in level trenches on hillslopes.
Low-quality forest improvement (LQFI)		Improving infertile forest located in the upslope and steep backslope positions by applying compound fertilizer on fish-scale-pits.
Economic fruit (EF)		Building new orchards on the middle and down slope positions or improving them under superior water and fertilizer conditions by constructing level terraces, drainage ditches, storage ditches, irrigation facilities and roads, planting economic fruit (e.g., chestnut, waxberry), and interplanting grasses and Fabaceae (Leguminosae) plants.

Table A.2 Environmental effectiveness and cost–benefit knowledge of the four best management practices (BMPs) within 5 years after implementation (adapted from Shen et al. (under review))

BMP	Year	Environmental effectiveness ¹						Cost–benefit (CNY 10,000/km ²)		
		OM	BD	PORO	SOL_K	USLE_K	USLE_P	Initial	Maintain	Benefits
CM	1	1.50	0.98	1.02	2.21	0.78	0.90	15.50	1.50	0.00
	2	1.62	0.97	1.03	4.00	0.99	0.90	0.00	1.50	0.00
	3	1.69	0.95	1.05	3.35	0.70	0.90	0.00	1.50	2.00
	4	1.74	0.94	1.06	3.60	0.60	0.90	0.00	1.50	2.00
	5	1.77	0.92	1.08	5.24	0.26	0.90	0.00	1.50	2.00
ABH MP	1	1.30	0.99	1.01	1.39	0.71	0.50	87.50	1.50	0.00
	2	1.36	0.98	1.02	1.38	0.89	0.50	0.00	1.50	0.00
	3	1.40	0.97	1.03	1.26	0.76	0.50	0.00	1.50	6.90
	4	1.42	0.96	1.04	1.15	0.75	0.50	0.00	1.50	6.90
	5	1.42	0.95	1.05	1.07	0.80	0.50	0.00	1.50	6.90
LQFI	1	2.80	0.98	1.02	1.54	0.88	0.50	45.50	1.50	0.00
	2	3.22	0.96	1.04	2.00	0.80	0.50	0.00	1.50	0.00
	3	3.47	0.94	1.07	2.76	0.60	0.50	0.00	1.50	3.90
	4	3.66	0.92	1.09	2.53	0.69	0.50	0.00	1.50	3.90
	5	3.8	0.90	1.11	2.38	0.73	0.50	0.00	1.50	3.90
EF	1	1.20	0.99	1.01	0.90	1.10	0.75	420.00	20.00	0.00
	2	1.23	0.98	1.02	1.16	1.06	0.75	0.00	20.00	0.00
	3	1.25	0.96	1.04	0.95	0.70	0.75	0.00	20.00	0.00
	4	1.26	0.95	1.05	1.60	0.65	0.75	0.00	20.00	0.00
	5	1.30	0.94	1.06	1.81	0.76	0.75	0.00	20.00	60.30

Note. ¹ environmental effectiveness of BMPs includes soil property parameters [organic matter (OM), bulk density (BD), total porosity (PORO), and soil hydraulic conductivity (SOL_K)] and universal soil loss equation (USLE) factors [soil erodibility factor (USLE_K) and conservation practice factor (USLE_P)]. Values in each column represent relative changes (multiplying) and, thus, have no units. For example, OM would increase in ratios of 1.50, 1.62, 1.69, 1.74, and 1.77, respectively, after implementing CM within 5 years. The conservation practice factor USLE_P will not change within 5 years.

CM, closing measures; ABHMP, arbor–bush–herb mixed plantation; LQFI, low-quality forest improvement; EF, economic fruit.

Shen Shen: Conceptualization, Methodology, Software, and Writing - Original Draft.
Cheng-Zhi Qin: Conceptualization, Supervision, Writing - Review & Editing, and Funding acquisition. **Liang-Jun Zhu:** Conceptualization, Methodology, Writing - Review & Editing, and Funding acquisition. **A-Xing Zhu:** Supervision and Funding acquisition.